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5.1-3 Angular momentum, kinetic energy of a rigid body. Inertia tensor, principal axes : Hwk #7, Ch 4: 4, 15, 21, 23, 24 (due Wed Nov 1, 11:30am) Solutions: 10 - Oct 30 - Nov 3 : 5- Rigid Body Motion : 5.3-5 Inertia tensor, principal axes Euler equations: 5.6-7 Torque free motion Heavy Symmetrical top Earth's wobble: look at the real data: 5.7 ...

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Goldstein, 3rd edition, Chapter 4, problem 15; Goldstein, 3rd edition, Chapter 4, problem 21, 24, 25; Comments: Problem 4.21: To fill in more details about the problem, assume that you are located in the northern hemisphere at a latitude of α . You should also pick a local coordinate system which has its z -axis normal to ground.

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$5^2 n_1 (23) = T_j (24)$ So (22) becomes $Z^2 H + T_j \dot{t} = 0$ (25) which is the required form of Hamilton's principle. 3 Goldstein 8.9 The constraints can be incorporated into the Lagrangian L by defining a "constrained Lagrangian" L_c , as $L_c(q; \dot{q}; t) = L(q; \dot{q}; t) + X_k k(q; p; t)$ (26)

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